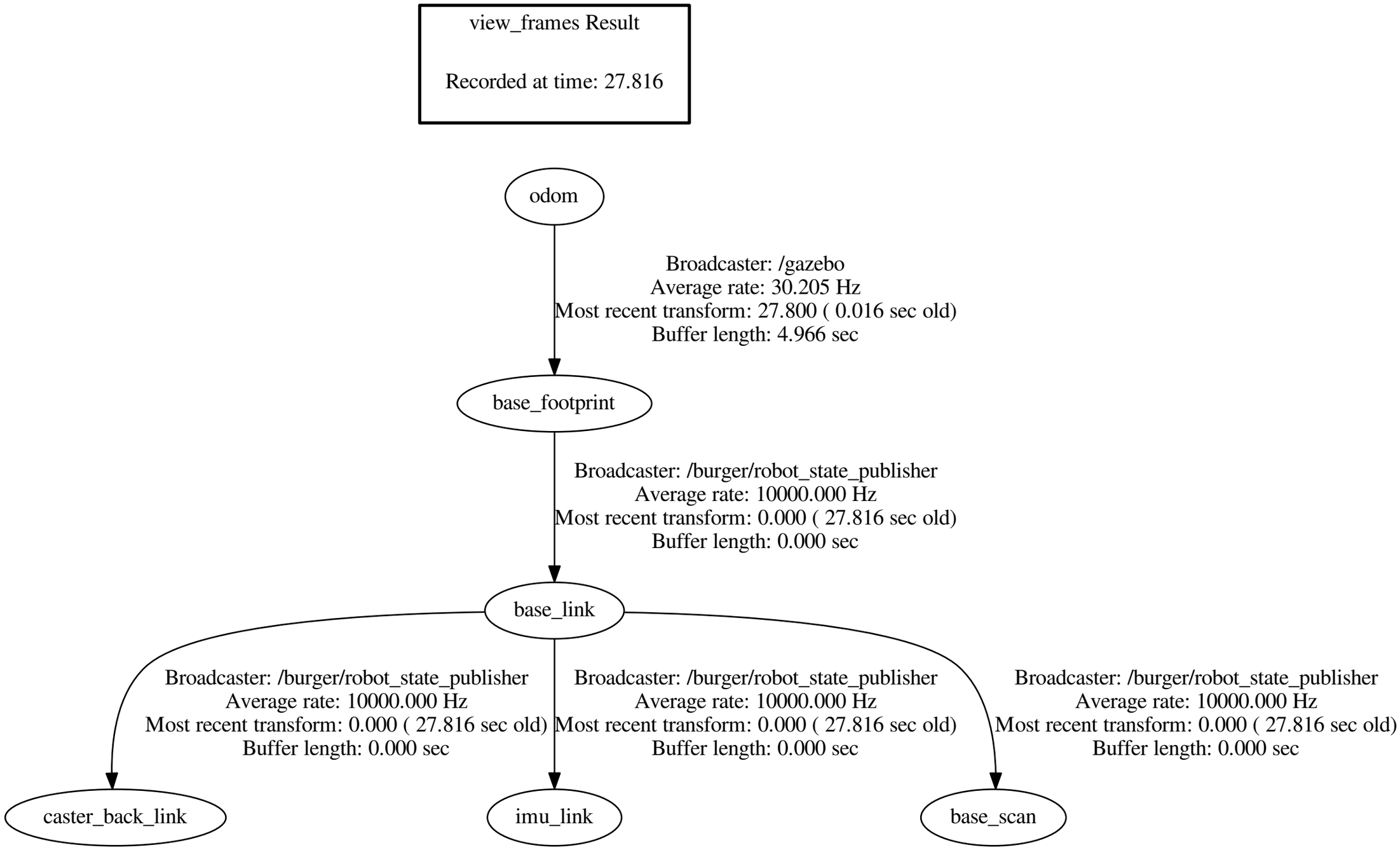
view_frames Result
Recorded at time: 27.816
odom
Broadcaster: /gazebo
Average rate: 30.205 Hz
Most recent transform: 27.800 (0.016 sec old)
Buffer length: 4.966 sec
base_footprint
Broadcaster: /burger/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (27.816 sec old)
Buffer length: 0.000 sec
base_link
Broadcaster: /burger/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (27.816 sec old)
Buffer length: 0.000 sec
Broadcaster: /burger/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (27.816 sec old)
Buffer length: 0.000 sec
Broadcaster: /burger/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (27.816 sec old)
Buffer length: 0.000 sec
caster_back_link
imu_link
base_scan